Marathon Motors
TerraMAX Series
INSTALLATION, OPERATION & MAINTENANCE INSTRUCTIONS
GES 4.0

For Industrial AC Induction Motors
80 – 355 Frames (IEC)

Regal Beloit America, Inc. 100 E. Randolph Street, Wausau, WI 54401 USA
The TerraMAX TCA series motors are designed and manufactured to be robust and reliable with minimal maintenance. The following items should be taken into consideration to ensure a trouble free installation and reliable operation throughout the motor life.

**Inspection**

TerraMAX motors are delivered through safe and reliable transport in appropriate packing to avoid damage during transit. On receipt of the motor thoroughly inspect the unit for any transit damage, if needed be in the presence of an insurance agent. Any equipment damage or shortfall should be immediately advised to the nearest Regal regional office.

Check the following:

- Rating plate details and enclosure are as ordered
- Shaft turns freely (in absence of shaft locking clamp)
- Condensation drain holes are in the correct position for the motor mounting application (they should be located at the lowest point of the motor when it is in its operating position)
- If the winding is Insulation Resistance (IR) tested to earth, ensure that the thermal protectors are not inadvertently damaged. (The thermistor leads should be shorted together whilst IR testing takes place)

**Storage**

When the motor is not for immediate use store as follows:

- Clean and dry location
- Free from vibration (vibration can damage bearings)
- Shaft locking clamps, where supplied, are fitted securely
- Remove shaft locking clamps and turn rotor by one full rotation at least once a fortnight and replace shaft locking clamps
- Anti-condensation heaters, where fitted, should be energized if the environment is likely to be damp

**Installation**

The following items should be considered on installation to ensure reliable operation of the motor:

**Surroundings**

- Ensure that the motor is properly protected against ingress of oil, water or dust especially if construction work is in progress around the motor,
- Ensure air intake is not obstructed. Refer to dimension BL in the catalogue,
- When installing hazardous location motors, make sure that the zone and gas group or dust and temperature classification on motor nameplate are complied with.

**Mounting**

- Bed plates or slide rails should be firmly fixed to a solid, level foundation to ensure the motor remains rigid and vibration free
- Shims or packers (if required) must be of adequate size and placed adjacent to and between base fixing screws
- Protective transport coatings on shafts and/or flanges must be removed prior to connection to the driven load
- A light coating of grease to shafts and/or flanges will inhibit corrosion during service and assist removal of pulleys or couplings

GES 4.0
Pulleys and couplings

- Pulleys or couplings should be independently balanced with a half key as the motor rotor is balanced with a half key during manufacture.
- In fitting pulleys or couplings to the motor shaft care must be taken to ensure the roller/ball bearings are not damaged. Both shaft and coupling bore should be cleaned and lubricated. If the fit is still too tight, the pulley or coupling should be pre-heated in air or oil to enable easy assembly.
- Shock methods must not be used in fitting or removing pulleys or couplings. Proper wheel or pulley removers should be used to prevent shaft and bearing damage. Tapped holes are provided in shaft extensions to assist in the fitment of couplings and/or pulleys.

Pulley and belts

- If the motor is to be coupled to the load using pulleys and belts it is important to ensure that the belt tension does not exceed the safe working radial load of the motor. Excessive radial load will lead to reduced bearing life with the potential of breaking the motor shaft. Because of this care must be taken to ensure the correct selection of pulley size and type (toothed, vee or flat) and this is best done in consultation with the transmission supplier.
- The belt manufacturer’s recommendations for installation, alignment and tensioning must be strictly adhered to when fitting belt drives.

Alignment

- Great care must be taken in aligning the complete machine, since misalignment can cause rapid deterioration of bearings and lead to other mechanical failures due to the stress produced.
- After final tightening of foundation bolts, machine alignment should be rechecked as bed plates could move and/or distort during machine mounting.
- No end thrust should be applied without express approval.
- When slide rails are used in conjunction with pulley drives, the adjusting screw ends should be positioned between the motor and load at drive shaft end and the other diagonally opposite. This helps speedy and accurate belt aligning, tensioning and replacement.

The correct alignment of the motor pulley with the load pulley is imperative. Both these pulley’s must have matched centre distances between grooves and alignment must be carried out using a suitable metal straight edge or other recommended tools to ensure parallel offset or angular displacement of the pulley’s with respect to each other is inside permissible limits as recommended by the transmission supplier. Correct alignment will result in a uniform distribution of belt tension across the width of the pulley (and the motor shaft) and ensure design life of both the belts and bearings is achieved.

Note: The pulley should always be mounted firmly against the shaft shoulder and should be a firm fit onto the shaft. Impact force must not be used.
As a general rule the midpoint of the applied force should be at the midpoint of the shaft and it is good engineering practice to mount the motor pulley with hub and locking screw at the shaft end.

Direct coupled
Where direct coupling of the motor is required, proper alignment must be achieved to prevent bearing damage to both motor and load.

For parallel offset, use a straight edge or other recommended tools, as shown below.

Excessive angular displacement must also be prevented. The recommended method to achieve correct angular alignment is shown below.

Axial load
Where motors with standard bearings are required to be mounted in either vertical shaft up or vertical shaft down orientation, there are limits on the axial forces that must not be exceeded. This also applies to horizontal mounted motors with certain loads that produce axial thrust. Axial loads exceeding those listed in the catalogue will reduce bearing life and may lead to internal motor damage.

Where higher than recommended axial loads are necessary different bearing types will be required. (Refer to Regal regional location).

There are various cooling formats for electric motors with IC411 (totally enclosed fan cooled) as the most common type that is used on our TCA motors. This type of cooling of motor is achieved by a fan mounted at the non-drive end, inside a fan cowl, which has an air inlet end, inside a fan cowl, which has an air inlet grill at the rear. Air is drawn in through the grill and the fan distributes the airflow along the fins of the motor body. The fan is designed for either direction of rotation (unless otherwise indicated on the fan cowl).

With TEFC motors it is important that the cooling fins remain clear of debris to allow the airflow to be fully effective in maintaining motor winding temperature within the design limits.

It is equally important to ensure the installation provides good unrestricted access to normal ambient air at the fan entry point at all times and that inlet grill is clear of contaminants. Refer to dimension BL below.

<table>
<thead>
<tr>
<th>Motor frame</th>
<th>Dimensions BL [ mm ]</th>
</tr>
</thead>
<tbody>
<tr>
<td>80 - 100</td>
<td>50</td>
</tr>
<tr>
<td>112 – 132</td>
<td>75</td>
</tr>
<tr>
<td>160 – 180</td>
<td>125</td>
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<tr>
<td>200 – 280</td>
<td>175</td>
</tr>
<tr>
<td>315 - 355</td>
<td>225</td>
</tr>
</tbody>
</table>
Hazardous location motors

Standard motors in the range of frame sizes 80 to 355 with appropriate modifications are certified for use in hazardous areas as below.

Non-sparking motors / Dust ignition-proof motors

Ex nA, Zone 2, Group II, Temperature class T3, $T_{\text{Amb}}$-20°C TO +50°C, 

Ex tc, Zone 22, Group III, Temperature class T200, $T_{\text{Amb}}$-20°C TO +50°C,

<table>
<thead>
<tr>
<th>Brand</th>
<th>Marking Code</th>
<th>Certification #</th>
<th>Contact Details</th>
</tr>
</thead>
<tbody>
<tr>
<td>marathon® Motors</td>
<td>Ex II 3G Ex nA IIC T3</td>
<td>IECEx UL 17.0014X</td>
<td>Regal Beloit America, Inc. 100 E. Randolph St. Wausau, WI 54401 USA</td>
</tr>
<tr>
<td></td>
<td>Gc IP55</td>
<td>DEMKO 17 ATEX 1836X</td>
<td></td>
</tr>
<tr>
<td></td>
<td>Ex II 3D Ex tc IIIIB T200 Dc IP66</td>
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<tr>
<td>cemp®</td>
<td>Ex II 3 G Ex nA IIC T3</td>
<td>IECEx UL 17.0104X</td>
<td>CEMP S.r.l. Via Piemonte 16-20030 SENAGO (Milan) - ITALY</td>
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<tr>
<td></td>
<td>Gc IP55</td>
<td>DEMKO 17 ATEX 1952X</td>
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<td>Ex II 3 G Ex nA IIC T3</td>
<td>IECEx UL 17.0111X</td>
<td>Regal Beloit Wuxi Co., Ltd. 6 Xiangge Road, Hudai Town, Wuxi City, Jiangsu, China</td>
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<tr>
<td></td>
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<td>marathon® Motors</td>
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<td>IECEx UL 17.0112X</td>
<td>Regal Beloit Australia Pty Ltd 19 Corporate Avenue, Rowville, VIC 3178 Australia</td>
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<tr>
<td></td>
<td>Gc IP55</td>
<td>DEMKO 17 ATEX 1964X</td>
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</tr>
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<td></td>
<td>Ex II 3D Ex tc IIIIB T200 Dc IP66</td>
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<td>marathon® Motors</td>
<td>Ex II 3 G Ex nA IIC T3</td>
<td>IECEx UL 17.0113X</td>
<td>Regal Beloit Australia Pty Ltd 7 Mahogany Court, Willawong, QLD 4110 Australia</td>
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<td>Gc IP55</td>
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<td></td>
<td>Ex II 3D Ex tc IIIIB T200 Dc IP66</td>
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<tr>
<td>marathon® Motors</td>
<td>Ex II 3 G Ex nA IIC T3</td>
<td>IECEx UL 17.0114X</td>
<td>Regal Beloit New Zealand Ltd 18 Jomac Place, Avondale Auckland, New Zealand</td>
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<td>DEMKO 17 ATEX 1966X</td>
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<td>Ex II 3D Ex tc IIIIB T200 Dc IP66</td>
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<tr>
<td>marathon® Motors</td>
<td>Ex II 3 G Ex nA IIC T3</td>
<td>IECEx UL 17.0115X</td>
<td>Regal Beloit South East Asia Pte Ltd, 12 Tuas Loop, Singapore 637346</td>
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<td></td>
<td>Gc IP55</td>
<td>DEMKO 17 ATEX 1967X</td>
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<td></td>
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<td></td>
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<tr>
<td>rotor® nl®</td>
<td>Ex II 3 G Ex nA IIC T3</td>
<td>IECEx UL 17.0129X</td>
<td>Rotor BV Mors 1-5, 7151 MX, Eibergen, The Netherlands</td>
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<tr>
<td></td>
<td>Gc IP66</td>
<td>DEMKO 17 ATEX 1968X</td>
<td></td>
</tr>
<tr>
<td></td>
<td>Ex II 3D Ex tc IIIIB T200 Dc IP66</td>
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</table>
Dust Ignition Proof Motors / Increased Safety Motors

Ex tb, Zone 21, Group III, Temperature class T200, $T_{\text{Amb}} -20^\circ\text{C TO} +50^\circ\text{C}, \quad 0539$

Ex e, Zone 21, Group III, Temperature Class T3, $T_{\text{Amb}} -20^\circ\text{C TO} +50^\circ\text{C}, \quad 0539$

<table>
<thead>
<tr>
<th>Brand</th>
<th>Marking Code</th>
<th>Certification #</th>
<th>Contact Details</th>
</tr>
</thead>
<tbody>
<tr>
<td><strong>marathon Motors</strong></td>
<td>Ex II 2D Ex tb IIIB T200 Db IP66 Ex II2G Ex e IIC T3 Gb IP55</td>
<td>IECEx UL 17.0014X DEMKO 18 ATEX 1982X</td>
<td>Regal Beloit America, Inc. 100 E. Randolph St. Wausau, WI 54401 USA</td>
</tr>
<tr>
<td><strong>cemp</strong></td>
<td>Ex II 2D Ex tb IIIB T200 Db IP66 Ex II2G Ex e IIC T3 Gb IP55</td>
<td>IECEx UL 17.0104X DEMKO 18 ATEX 2068X</td>
<td>CEMP S.r.l. Via Piemonte 16-20030 SENAGO (Milan) - ITALY</td>
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<td><strong>marathon Motors</strong></td>
<td>Ex II 2D Ex tb IIIB T200 Db IP66 Ex II2G Ex e IIC T3 Gb IP55</td>
<td>IECEx UL 17.0111X DEMKO 18 ATEX 2073X</td>
<td>Regal Beloit Wuxi Co., Ltd. 6 Xiangge Road, Hudai Town, Wuxi City, Jiangsu, China</td>
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<td><strong>marathon Motors</strong></td>
<td>Ex II 2D Ex tb IIIB T200 Db IP66 Ex II2G Ex e IIC T3 Gb IP55</td>
<td>IECEx UL 17.0112X DEMKO 18 ATEX 2069X</td>
<td>Regal Beloit Australia Pty Ltd 19 Corporate Avenue, Rowville, VIC 3178 Australia</td>
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<td><strong>marathon Motors</strong></td>
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<td>IECEx UL 17.0113X DEMKO 18 ATEX 2070X</td>
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<td>IECEx UL 17.0114X DEMKO 18 ATEX 2071X</td>
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<td>IECEx UL 17.0115X DEMKO 18 ATEX 2072X</td>
<td>Regal Beloit South East Asia Pte Ltd, 12 Tuas Loop, Singapore 637346</td>
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<tr>
<td><strong>rotor nl</strong></td>
<td>Ex II 2D Ex tb IIIB T200 Db IP66 Ex II2G Ex e IIC T3 Gb IP55</td>
<td>IECEx UL 17.0129X DEMKO 18 ATEX 2074X</td>
<td>Rotor BV Mors 1-5, 7151 MX, Eibergen, The Netherlands</td>
</tr>
</tbody>
</table>
Classification of zone, group and temperature category are in accordance with the standards applied in the certificates. A detail explanation of these is available in the product catalogue.

The hazardous location motor nameplates also carry the certification number in addition to the marking codes for the specific protection levels. Details of the standards to which these are certified are available on the actual certificates, copies of which can be accessed from the website or obtained from the nearest Regal regional office.

NOTE: Only motors that carry nameplates indicating Ex nA can be used in hazardous locations. Check nameplate before installing motors in hazardous locations.
Cable entries

Cable entries are via appropriate cable glands or conduits fitted to the threaded entries in the wall of the terminal box or the gland plate attached to it. Cable entries for various frame sizes are as per the following table:

<table>
<thead>
<tr>
<th>Motor frame</th>
<th>No. of entries</th>
<th>Entry size x pitch</th>
<th>Reference drawing for Ex motors</th>
</tr>
</thead>
<tbody>
<tr>
<td>80 - 132</td>
<td>2</td>
<td>M20x1.5-6H (or) M25 x 1.5-6H</td>
<td>TCA0811TB1 TCA13TB1</td>
</tr>
<tr>
<td>160 - 180</td>
<td>2</td>
<td>M25 x 1.5-6H (or) M32 x 1.5-6H (or) M40 x 1.5-6H</td>
<td>TCA1618TB1</td>
</tr>
<tr>
<td>200 - 280</td>
<td>2</td>
<td>M32 x 1.5-6H (or) M40 x 1.5-6H (or) M50 x 1.5-6H</td>
<td>TCA2022TB1 TCA2528TB1</td>
</tr>
<tr>
<td>315</td>
<td>2</td>
<td>M63x1.5-6H</td>
<td>TCA31TB1</td>
</tr>
<tr>
<td>355</td>
<td>4</td>
<td>M63x1.5-6H</td>
<td>TCA35TB1</td>
</tr>
</tbody>
</table>

Cable glands used by installer on hazardous location motors must be of IEC Ex certified type as appropriate to the installation requirements. Unused cable entries must be blanked off by installer using IEC Ex certified conduit stops as appropriate.

Cable glands and conduit stops must be of an IP Rating equal to or better than that of main motor as marked on the nameplate.

Vibration sensors and shaft encoders when fitted by the installer are to be appropriately certified by IECEx or ATEX for the same zone protection method(s) and temperature code.

Supply terminals

Supply terminals are located in terminal box. They are suitable for receiving crimped lugs on the supply cables. In addition the terminal box also houses an earthing terminal.

<table>
<thead>
<tr>
<th>Motor frame</th>
<th>Terminal size</th>
<th>Total Tightening torque-Steel Zn Plated Nm</th>
<th>Total Tightening torque-Brass Nm</th>
</tr>
</thead>
<tbody>
<tr>
<td>80 - 132</td>
<td>M5</td>
<td>4</td>
<td>3.2</td>
</tr>
<tr>
<td>160 - 180</td>
<td>M6</td>
<td>6</td>
<td>5</td>
</tr>
<tr>
<td>200 - 225</td>
<td>M8</td>
<td>12</td>
<td>10</td>
</tr>
<tr>
<td>250 - 280</td>
<td>M10</td>
<td>20</td>
<td>16</td>
</tr>
<tr>
<td>315</td>
<td>M12</td>
<td>31</td>
<td>25</td>
</tr>
<tr>
<td>355</td>
<td>M16</td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

Above mentioned Total Tightening Torque is nominal Torque

Electrical connection

TerraMAX motors are provided with two earthing bolt, one inside the terminal box and other on the motor frame. Depending on the cross-section of the line conductor, the earthing conductor cross-section must be:

<table>
<thead>
<tr>
<th>Line conductor cross-section</th>
<th>Earth conductor cross-section</th>
</tr>
</thead>
<tbody>
<tr>
<td>≤ to 25mm²</td>
<td>Same Section</td>
</tr>
<tr>
<td>Between 25mm² and 50mm²</td>
<td>25mm²</td>
</tr>
<tr>
<td>&gt; 50mm²</td>
<td>≥ 50% of the section</td>
</tr>
</tbody>
</table>
• Ensure all electrical connections are solid and continuous
• Check motor starter and overloads for correct rating and trip setting
• All circuit breakers, HRC fuses/protective devices associated with the motor must be rated to suit motor running current & starting characteristics
• Supply cables must be appropriately selected considering the voltage drop,
• When using long supply cables with Adjustable Speed Drive, check with Regal regional for proper recommendations to avoid high voltage transients occurring at motor terminals
• Check the connection diagram on the motor terminal box and make sure the supply leads are properly connected considering the supply phase sequence
• Ensure that the supply cable termination on to the motor terminal board is firm without loss of strands while using crimped lugs and all washers are used in the correct order as provided
• Ensure enough clearances are provided between supply cable lugs & to earth especially so in case of hazardous location motors
• Ensure that proper earth connection is made with all washers as provided,
• If using conduit for the supply leads, ensure the conduit is completely threaded in and seal the threads appropriately
• If RTDs of hazardous location motors are connected to monitor the winding temperature, the maximum voltage to the RTDs must be kept to 90V(peak) or below
• The stator RTDs and thermistors can be connected via a standard industrial controller provided that the controller is located in a safe area

Initial start up
Prior to initial start-up check the following-
• Insulation resistance of motor winding to earth to be over 1 MΩ for motors up to 600V and over 10 MΩ for over 600V
• Thermistors or RTDs if fitted, should be checked for continuity with a multimeter
• Ensure thermistors are wired up to the motor protection relay as to trip the supply to the motor in the event of an over temperature
• Do not megger test thermal protective devices across their terminals. Short the entire protector leads together and apply the test voltage between the shorted leads and earth and/or phases
• Hazardous location motors supplied by an Adjustable Speed Drive must have the thermal protection devices connected into the motor control circuit in such a manner as to disconnect the source of supply in the event of an over temperature thus preventing the nominated temperature class being exceeded
• Anti-condensation heaters if provided must be so connected as to switch on when the motor supply is disconnected and switch off when the motor supply gets connected
• Ensure that the supply voltage and frequency correspond to the motor nameplate ratings
• Ensure shaft turns freely before initial start
• Measure winding resistance between supply terminals and record in the log book
Operation

- Before energizing the motor make sure that the terminal box lid is closed and secured with appropriate clearance to live parts. Make sure that appropriate earthing is done
- If an earthing ring and earth brush are provided, make sure that the earthing ring is clean and the earth brush makes a good contact with the earthing ring. This applies for the Safe Area motors
- Make sure that the coupling and/or transmission is adequately guarded for safety
- Check the mounting bolts and/or flanges are firmly secured
- Make sure of no loose objects around that may be sucked by the cooling fan on the motor
- Make sure that the load applied is within the nameplate specification,
- Make sure that the ambient temperature is inside 40°C or nameplate specification
- Avoid frequent starting of motor. Refer to motor catalogue or nearest Regal regional office for recommendation on frequency and duration of starts
- If an Adjustable Speed Drive is used on Ex nA motor, follow the instructions on additional nameplate for converter supply in respect to applied load and frequency
- Check that the running current on no load and full load are reasonably balanced within 10% of the average and record the figures in the log book for future reference. Note that the current imbalance can be higher, typically 10 times the voltage imbalance if there is an imbalance in supply voltage
- Brake motors used in hazardous locations must have a limited number

of repeat stops to 20 per hour

Maintenance

Reliable, trouble free operation of a motor needs regular maintenance. Exact maintenance needs are based on the site conditions. To obtain reliable service from the motor, the following maintenance schedule may be used as a guide. An authorized service agent must carry out maintenance of hazardous location motors. Clean the surface of the motor with a damp cloth to minimize the risk of electrostatic discharge

A. Ensure air intake space is unobstructed
B. On a weekly basis use an air hose to ensure all air ways are clear and free of dust
C. Once every month, check motor for condensation. Replace drain plugs before starting if they are blocked or found missing
D. Do not wash the motor unless it is IP66 rated
E. On a quarterly basis-
   (i) Check the motor terminals for tightness and proper contact
   (ii) If terminal lug/s are discolored, re-terminate with fresh lugs
   (iii) Check operation of starting equipment, ensuring all terminations are tight
   (iv) Check mechanical operation of thermal overload if any.
   (v) Check mechanical operation of thermistor relays, if fitted
   (vi) Check operation of anti-condensation heaters, if fitted
   (vii) Check the earth ring and earth brush Length, if fitted. (For Safe Area Motors)
F. On a six monthly basis, in addition to the items in ‘E’ -
   (i) Check winding resistance between supply terminals and compare to original value and enter in log book.
   (ii) Check supply voltage at motor terminals and record in log book.
   (iii) Check bearing for abnormal noise/ overheating
G. On an annual basis, in addition to the items in ‘E’ and ‘F’:
(i) Re-grease the bearings as recommended under Lubrication & Bearings.
(ii) Completely disassemble stator, rotor apart and clean thoroughly.
(iii) Check bearings for wear/damage – replace as necessary.
(iv) Check all bolts and nuts for cracks or damage – replace as necessary.
(v) Check all holding down bolts for signs of fatigue or damage – replace as necessary.
(vi) After re-assembly, check and record in the log book: Insulation resistance by megger No load current and voltages Full load current and voltages. Ensure that these figures compare well with the records in the log book.
(vii) Check and ensure that the cooling fan is operational.

Open (re-greaseable) bearings

It should be noted that for motors fitted with Ball and Roller bearings, the lubrication intervals for both bearings should be based on the roller bearing data.

The re-lubrication intervals recommended are calculated on the basis of normal working conditions.

Note: Under hazardous conditions please contact Regal regional or the bearing manufacturers catalogue. Air operated grease guns should not be used.

Replenishment of grease media should be by means of a hand held grease gun while motor is running with relief plate removed.

The lubricating ability of grease (over time) depends primarily on the type of grease, the size of the bearing, the speed at which the bearing operates and the severity of the operating conditions. Longer bearing life can be obtained of the listed recommendations are followed:

NOTE: If lubrication instructions are provided on the motor nameplate, the nameplate instructions will supersede these instructions. Motors marked “Permanently Lubricated” do not require additional service.

CAUTION: BEARING/MOTOR DAMAGE WARNING

Lubricant should be added at a steady, moderate pressure. If added under heavy pressure, bearing shield(s) may collapse. Over greasing bearings greatly increases bearing friction and can cause premature bearing and/or motor failure.

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Lubrication & Bearings

Sealed bearings

The required replacement interval for sealed bearings is generally determined by the grease life which is dependent on operating temperature, operating speed, the limiting speed of the bearing and the type of grease. Under normal operating conditions the following relationship applies for sealed bearings:

$$\log t = 6.54 - 2.6 \frac{n}{N} - (0.025 - 0.012) \frac{T}{N}$$

where,

- $t$ = Average grease life (hours)
- $N$ = Bearing limiting speed with grease lubrication (RPM)
- $T$ = Operating temperature (°C)

For further information, please contact your nearest Regal regional office for advice.
GREASE TYPE (unless nameplate states otherwise):
Use lithium based grease such as Mobil Polyrex-EM or equivalent unless otherwise specified. Motors requiring extra high temperature for use in ambient temperatures above 40°C, use grease such as Magnalube G or equivalent.

When re-greasing bearings ensure that the correct type of grease is used. If in doubt about the existing grease type, clean out the old grease thoroughly from bearings and bearing housing, prior to re-greasing.

WARNING:
NEVER MIX GREASE OF DIFFERENT TYPES

LUBRICATION PROCEDURE:
NOTE: Frames 80 through 180 use sealed bearings and are not re-greaseable. Frames 200 through 355 use open re-greaseable bearings.

CAUTION: BEARING DAMAGE WARNING
Added grease must be compatible with the original equipment’s grease. If a grease other than those stated herein is to be used, contact the motor manufacturer. Nameplate information supersedes grease type referenced in this section. New grease must be free of dirt. Failure to follow these instructions and procedures may result in bearing and/or motor damage. For an extremely dirty environment, contact the motor manufacturer for additional information.

Step 1: Clean the grease inlet and drain plugs prior to re-greasing.
Step 2: Remove grease inlet and drain plugs
Step 3: Add grease per below Table.
Step 4: Re-install grease inlet and drain plugs and ensure plugs have at least 5 full threads of engagement with motor.

CAUTION: GREASE DRAIN PLUGGED
Old grease may completely block the drain opening and must be mechanically removed prior to re-greasing. Forcing a blocked drain open by increased greasing pressure may collapse bearing shields and/or force excess grease through the bearings and into the motor.
Recommended Grease Replenishment Intervals (Hours)¹)

<table>
<thead>
<tr>
<th>Bearing number(2)</th>
<th>Bearing bore</th>
<th>Grease Qty</th>
<th>3000 r/min</th>
<th>1500 r/min</th>
<th>1000 r/min</th>
<th>750 r/min</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td>[mm]</td>
<td>[g]</td>
<td>Ball</td>
<td>Roller</td>
<td>Ball</td>
<td>Roller</td>
</tr>
<tr>
<td>6312/NU312</td>
<td>60</td>
<td>22</td>
<td>3000</td>
<td>1500</td>
<td>9000</td>
<td>4500</td>
</tr>
<tr>
<td>6313/NU313</td>
<td>65</td>
<td>24</td>
<td>2000</td>
<td>1000</td>
<td>8000</td>
<td>4000</td>
</tr>
<tr>
<td>6314/NU314</td>
<td>70</td>
<td>26</td>
<td>1500</td>
<td>750</td>
<td>4000</td>
<td>2000</td>
</tr>
<tr>
<td>6316/NU316</td>
<td>80</td>
<td>38</td>
<td>1000</td>
<td>500</td>
<td>-</td>
<td>-</td>
</tr>
<tr>
<td>6317/NU317</td>
<td>85</td>
<td>38</td>
<td>1000</td>
<td>500</td>
<td>4000</td>
<td>2000</td>
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<tr>
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<td>90</td>
<td>45</td>
<td>-</td>
<td>-</td>
<td>3000</td>
<td>1500</td>
</tr>
<tr>
<td>6322/NU322</td>
<td>95</td>
<td>60</td>
<td>-</td>
<td>-</td>
<td>3000</td>
<td>1500</td>
</tr>
</tbody>
</table>

¹) Based on maximum grease service life of 20,000 hours  ²) Refer to Nameplate / Motor to confirm bearing size.

Motors – PWM Drives

The TerraMAX motor performs excellently without cogging at the low speed when operating in conjunction with a PWM (Pulse-Width Modulated) drive.

The graph below shows the TerraMAX motor’s loadability with a frequency converter.